

6.854 Optional Lecture: LINK-CUT TREES

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□ Roadmap.

§1. Goal [Op.]

§2. Link-cut Tree Structure

§3. Implementations

§4. Amortized Analysis

§5. Applications on Blocking-flows

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[Notes will be provided]

□ Goal.

- represent a forest of rooted trees
- each node has an arbitrary # of unordered children
- $\text{FIND-ROOT}(v)$: return the root of the tree that contains v .
- $\text{CUT}(v)$: delete the edge between v and $\text{par}(v)$.
- $\text{LINK}(v, w)$: make v a new child of w
(user guarantee: v is the root of some tree)
- Will consider $\text{UPDATE}/\text{FIND-MIN}$ to deal with cap./vol. later.

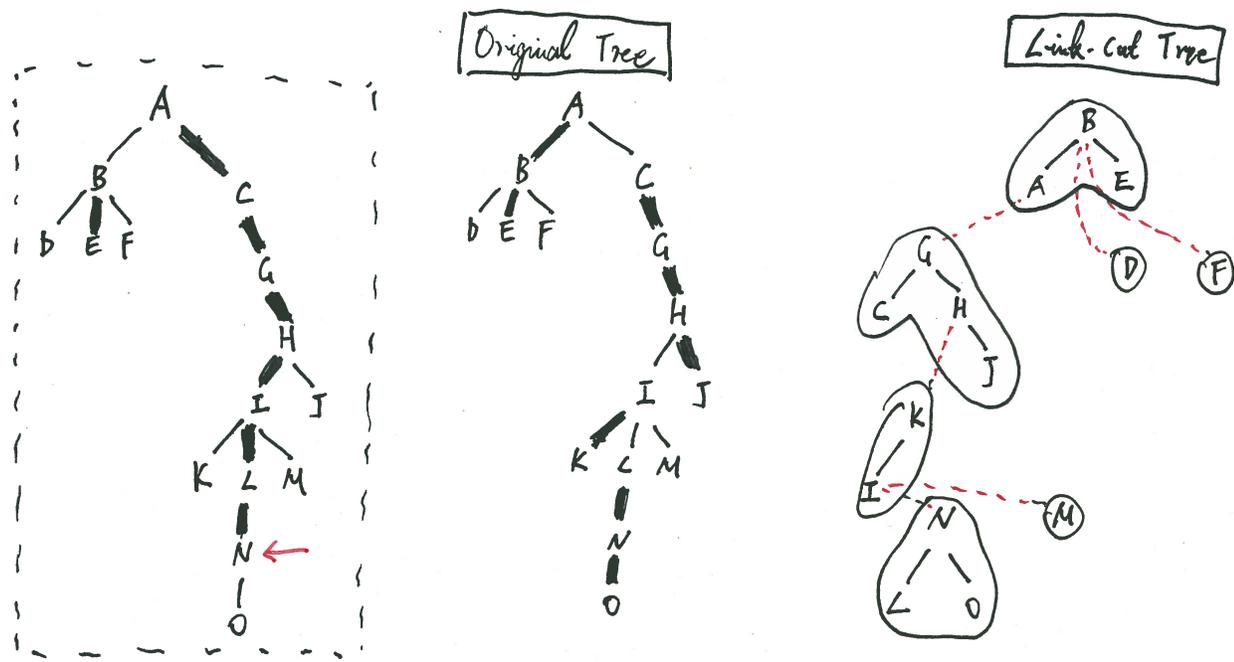
□ Warm-Up.

- Maintain the tree $\Rightarrow O(1)$ cut/link but $O(n)$ FIND-ROOT .
- No CUT op. $\Rightarrow O(d(w))$ $\text{LINK}/\text{FIND-ROOT}$ using disjoint-union
- [Sleator Tarjan '82] "A data structure for dyn. trees"
 $O(\log n)$ amortized, using Link-cut Trees.

□ LINK-CUT TREES.

- Intuition. $\left\{ \begin{array}{l} \text{if there is a single chain — use a splay tree, ordered by depth} \\ \text{otherwise, do path decomposition, each path by a splay tree.} \end{array} \right.$

- A node has been accessed if was passed to some op. above.
- For a node v , its preferred child is the one that contains the last accessed node in $T(v)$.
- A preferred edge is (v, w) where w is v 's preferred child.
- A preferred path is a path of preferred edges. [Draw Original Tree]



- Represent (each of) the original tree as a tree of auxiliary trees, one for each preferred path
- Each auxiliary tree is a (binary) splay tree keyed by depth [left = closer to the root]
- [Draw Link-cut Tree]
- Each root of the auxiliary tree has a path-parent pointer [except for the root]
- [can't store parent-to-child pointers]

□ Operations / Implementations

- ACCESS(v): no actual change to the original tree but change the preferred-path decomposition

[Go to the example, ACCESS(N)]

- SPZAY(v). [bring v to the top of his auxiliary tree], right = descendants on original tree

- path-parent(right(v)) ← v, right(v) ← null [setting par(right(v)) ← null]

- WHILE v ≠ root of the link-cut tree DO. (*)

 Δ w ← path-parent(v)

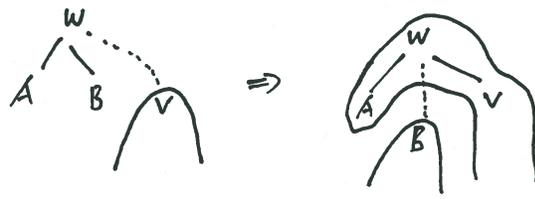
 Δ SPZAY(w)

 Δ path-parent(right(w)) ← w, right(w) ← v

 Δ path-parent(v) ← null

 Δ v ← w.

- SPZAY(v')



• FIND-ROOT(v): - ACCESS(v)

 - w ← smallest elem. in the auxiliary tree of v.

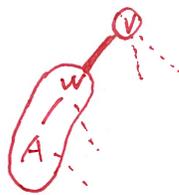
 - SPZAY(w), return w.

• CUT(v): - ACCESS(v)

 - left(v) ← null [no need to set up the path-parent]

• LINK(v, w): - ACCESS(v), ACCESS(w)

 - left(v) ← w.



□ Amortized Analysis - $O(\log^2 n)$

• Suffices to show ACCESS(v) is in $O(\log^2 n)$ amortized.

• Each SPZAY $O(\log n)$, suffices to show Loop (*) has $O(\log n)$ iter. (amortized)

Am I cheating?	n A ops.	$n \log n, 1, 1, \dots, 1$	$\Rightarrow \log n$ amortized
	n B ops.	$n \log n, 1, 1, \dots, 1$	$\Rightarrow \dots$
	Together	$n^2 \log^2 n / n = n \log^2 n$?	

$\underbrace{\text{Access}}_{SSS \dots S}$	$\underbrace{\text{Access}}_{SS}$	\dots	$\underbrace{\text{Access}}_{SS \dots S}$	† Access $\Rightarrow \dagger \log n$ SPZAY $\Rightarrow \dagger \log^2 n$ time
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• Heavy-Light Decomposition

- An edge $(v, \text{par}(v))$ is heavy if $\text{size}(v) > \frac{1}{2} \text{size}(\text{par}(v))$.

- $\text{light-depth}(v) := \# \text{ of light edges } \text{root} \leftrightarrow v. \quad O(\log n)$

- [An edge in the original graph can be light/heavy, preferred/unpreferred]

• # of iter. in $(*) = O(\# \text{ edge that become preferred})$

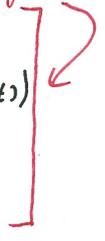
• At most $O(\log n)$ of light edges will become preferred for each Access.

$\#(\text{heavy edges become preferred}) \leq \#(\text{heavy edges become unpreferred}) + (n-1)$

$\leq \#(\text{light edges become preferred}) + (n-1) \quad (+O(t))$

$\leq \cancel{O(t \log n)} \quad \underline{\text{for } t \text{ Access}}$
 $O(t \cdot \log n)$

This part will be made clear on the 6th page



$\Rightarrow O(\log n)$ iter. amortized.

□ Amortized Analysis - $O(\log n)$

• $\underline{I}(v) = \log s(v)$ $s(v)$: # nodes in the ~~auxiliary tree~~ link-cut tree [tree of aux. trees]

• Does not affect ops. in splay trees [imagine that we have weights now]

$\text{cost}(\text{splay}(v)) \leq 3(\log s(u) - \log s(v))$

where u is the root of the auxiliary tree that contains v .

• Access(v) takes $O(\log n)$ amortized, due to telescoping

• CUT(v): potential ↓ } of $\leq O(\log n)$.
LINK(v, w): potential ↑ }

□ Applications

• Let each edge be associated with a capacity

store it on the node, $c(v) := c(v, w)$ where w is v 's parent in the original tree.
 $c(\text{root}) := \infty$

• UPDATE(v, x): add x to all edges on $\text{root}(v) - v$.

• FIND-MIN(v): return min cap. node ~~in v 's path to root(v)~~
on $\text{root}(v) - v$

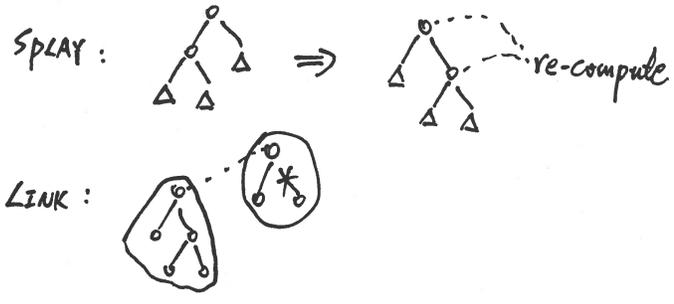
• Maintain the following extra fields

- $\Delta C(v) = c(v) - c(w)$ if $w = \text{par}(v)$ on the aux. (splay) tree.
= $c(v)$ if $v = \text{root}$

- ~~min(v)~~ = value of the min cap. node in subtree (v).
 $\Delta \text{min}(v) = \text{min}(v) - c(v) \leq 0$

- $\text{argmin}(v)$

• All in $O(1)$ to maintain:

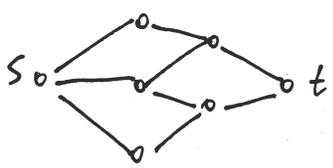


• UPDATE (v, x): ACCESS (v), $\Delta(v) \leftarrow \Delta(v) + x$

FIND-MIN (v, x): ACCESS (v), return $\text{argmin}(v)$.

CAP (v): ACCESS (v), return $\Delta C(v)$.

□ Blocking-Flow



STEP 0: each vertex forms an ind. tree

STEP 1: $v \leftarrow \text{FIND-ROOT}(s)$

STEP 2: If $v \neq t$ { (Advance) select an edge (v, w) , LINK (v, w, cap)
(Retreat) if no such edge, for each (w, v) , if in, CUT (w) .

GOTO 1.

STEP 3: If $v = t$ (Augment), { $v \leftarrow \text{FIND-MIN}(s)$
UPDATE $(s, -\text{CAP}(v))$ GOTO 1.
CUT (v)

• $O(m \log n)$ alg. for blocking-flow, $\Rightarrow O(mn \log n)$ for max-flow.

□ Fixing a bug on page 4.

- I claimed earlier that $\#(\text{heavy edges become preferred}) \leq \#(\text{heavy edges become unpreferred}) + (n-1)$, since "a heavy edge must become unpreferred before it can be preferred again".
- The above claim is **INCORRECT!** The same mistake has also appeared in the lecture notes of 6.854 in 2007, and 6.851 in 2007.

- The correction is as follows:

$$\begin{aligned} \#(\text{heavy edges become preferred}) &\leq \#(\text{heavy-preferred edges get destroyed}) + (n-1) \\ &= \#(\text{heavy-preferred} \Rightarrow \text{unpreferred}) + \#(\text{heavy-preferred} \Rightarrow \text{light}) + (n-1). \\ &=: \textcircled{1} + \textcircled{2} + (n-1). \end{aligned}$$

- $\textcircled{1}$ can only happen in **ACCESS**. But, if a heavy edge gets unpreferred, there must be a light one that gets preferred (except one of them for each **ACCESS**). But, $\#(\text{light edges get preferred}) = O(\log n)$ for each **ACCESS**. In sum, $\textcircled{1} = O(t \log n) + t = O(t \log n)$.
- $\textcircled{2}$ can only happen during **LINK/CUT**.
 - It won't happen in **LINK**(v, w) because all edges on the way $w \leftrightarrow \text{root}$ are preferred after **ACCESS**(w), and they will only get heavier.
 - It happens in **CUT**(v). All edges on $v \leftrightarrow \text{root}$ will be preferred after **ACCESS**(v), but at most $O(\log n)$ of them ~~are~~ will become light. $\Rightarrow \textcircled{2} = O(t \log n)$
- $\Rightarrow \#(\text{heavy edges become preferred}) = O(t \log n)$.